

IF Module for LSM Controller <PROFINET>

LSM-PN-A



User's Manual - Instructions for use -

Read this document thoroughly before operating the product. After reading, retain it close at hand for future reference. This English language version of the document contains the original instructions.

> No. 99MBC156A Date of publication: June 1, 2023 (1)



Product names and model numbers covered in this document

| Product name | Model number |
|--|--------------|
| IF Module for LSM Controller <profinet></profinet> | LSM-PN-A |

Notice regarding this document

- Mitutoyo Corporation assumes no responsibilities for any damage to the product, caused by its use not conforming to the procedure described in this document.
- Upon loan or transfer of this product, be sure to attach this document to the product.
- In the event of loss or damage to this document, immediately contact the agent where you purchased the product or a Mitutoyo sales office.
- Read this document thoroughly before operating the product. In particular, be sure to fully understand "Safety Precautions" and "Precautions for Use".
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Conventions and Wording Used in This Document

Safety reminder conventions and wording warning against potential hazards

| A DANGER | Indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury . |
|-----------------|---|
| WARNING | Indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury. |
| | Indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury. |
| NOTICE | Indicates a situation which, if not avoided, may result in property damage. |
| | Electricity |
| 4 | Alerts the user to a specific hazardous situation that means "Caution, risk of electric shock". |
| | Hot surface |
| | Alerts the user to a specific hazardous situation that means "Caution, risk of burns due to high temperature". |
| | Flammable material |
| | Alerts the user to a specific hazardous situation that means "Caution, risk of igniting gas". |
| | Sharp element |
| | Alerts the user to a specific hazardous situation that means "Caution, risk of injury". |
| | Crushing of hands |
| | Alerts the user to a specific hazardous situation that means "Caution, risk of hand pinching". |
| | Optical radiation |
| | Alerts the user to a specific hazardous situation that means "Caution, risk of high-intensity light". |
| | |

Conventions indicating prohibited and mandatory actions

| \bigcirc | Indicates concrete information about prohibited actions. |
|------------|--|
| | Indicates concrete information about mandatory actions. |
| ļ | Indicates that grounding needs to be implemented. |

Conventions and wording indicating referential information or reference location



Indicates further information and details relevant for the operating methods and procedures that are explained in that section.



Indicates reference location if there is information that should be referred to in this document or an extraneous User's Manual.

Example: For details about XX, see 📰 "1.2 Features of This Product" on page 1 in "1 Introduction".

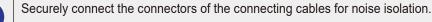
Safety Precautions

Read these "Safety Precautions" thoroughly before operating the product to use it properly. These safety precautions include such information as to prevent injury to the operator and other persons, damage to property and product defects. Be sure to observe these precautions carefully.

Precautions for this product

Image: CAUTION Image: Construction of the system in cases of a malfunction. Image: Construction of the system in case of a malfunction. Image: Construction of the system in case of a malfunction. Image: Construction of the system in case of a malfunction. Image: Construction of the system in case of a malfunction. Image: Construction of the system in case of a malfunction. Image: Construction of the system in case of a malfunction. Image: Construction of the system in case of a malfunction. Image: Construction of the system in case of a malfunction. Image: Construction of the system in case of a malfunction. Image: Construction of the system in case of a malfunction. Image: Construction of the system in case of a malfunction. Image: Construction of the system in case of a malfunction. Image: Construction of the system in case of a malfunction. Image: Construction of the system in case of a malfunction. Image: Construction of the system in case of a malfunction. Image: Construction of the system in case of a malfunction. Image: Construction of the consthe consthe construction of the construction of the cons

NOTICE



Tips

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Even if an error is displayed while measuring, it does not necessarily indicate a malfunction. See 🔝 "6 Troubleshooting" on page 37 to check the cause and solution.

Precautions for Use

- Use and handling of the product
- Use this product only by connecting to measuring instruments which supports this product.



Do not use this product for measuring instruments which does not support this product. For measuring instruments supported by this product, see []] "1.3 LSM System Diagram" on page 2.

• This product is for industrial usage.



Do not use this product for purposes other than for industrial usage.

• This product is a precision instrument.



Do not subject the product to drastic shocks such as dropping it, or exert excessive force upon it.
Do not disassemble or modify the product.

If the product is used beyond the conditions indicated in the specifications (E "7 Specifications" on page 39), be aware that the functions and performance cannot be guaranteed.

Environment for placement

This product is a precision electronic instrument and is designed for indoor use. To obtain the highest accuracy, take into account the following conditions when installing the product. Mitutoyo assumes no responsibility for accidents or failures that result from disregarding the following items.

| | Use the product in the following places. Where there is minimal dust and grit Dust or grit in the usage area will adversely affect the mechanical and electronic components inside the product. Where there are minimal vibrations If the product is going to be used in places where there are lots of vibrations, problems will be generated in the precision components being used, which will cause measuring performance to be impaired. If use in a place with vibrations is inevitable, take measures to reduce vibrations, such as laying an anti-vibration rubber mat under the product. Where the ambient temperature is from 0 °C through 50 °C Where the humidity is from 20 % RH through 85 % RH (without condensation) Where the altitude is 2000 m or lower If the product is used in places where the altitude exceeds 2000 m, it will cause measuring perfor- mance to be impaired. |
|------------|---|
| \bigcirc | Do not use or store the product in the following places where the temperature and humidity drastically fluctuate, because the product's functions and measurement results will be adversely affected and it will cause malfunction. Where exposed to direct sunlight If installing this product in a place exposed to direct sunlight, such as near a window, is inevitable, take measures to shade the product from the sun, such as using a curtain. Where extremely hot or cold Where there are risks of getting wet |

Tips

This product does not conform to the International Protection standard (IP standard). Sensors (LSM-02-A and LSM-30-A) are IP67 rated.

Maintenance

For information on the care of this product, see 🗐 "Laser Scan Micrometer <Controller> User's Manual" (separate document).

Electromagnetic Compatibility (EMC)

This product complies with the EMC Directive and the UK Electromagnetic Compatibility Regulations; however, if this receives electromagnetic interference that exceeds these requirements, it will be out of warranty and require appropriate measures.

This product is an industrial product, and is not intended to be used in residential environment. If this product is used in residential environment, this product may cause electromagnetic interference with other instruments. In such a case, it is required to take appropriate measures for preventing such electromagnetic interference.

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This product falls into the Catch-All-Controlled Goods and/or Catch-All-Controlled Technologies (including Programs) under Category 16 of Appended Table 1 of Export Trade Control Order or under Category 16 of Appended Table of Foreign Exchange Control Order, based on Foreign Exchange and Foreign Trade Act of Japan.

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Also, if an option is added or modified to add a function to this product, this product may fall under the category of List-Control Goods, List-Control Technology (including Programs) under Category 1 - 15 of Appended Table 1 of Export Trade Control Order or under Category 1 - 15 of Appended Table of Foreign Exchange Control Order, based on Foreign Exchange and Foreign Trade Act of Japan. In that case, if you intend re-export of the product from a country other than Japan, re-sale of the product in a country other than Japan, or re-providing of the technology (including Programs), you shall observe the regulations of your country. Please contact Mitutoyo in advance.

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When you intend exporting of this product to any of the European countries, it may be required to provide User's Manual(s) in English and Declaration of Conformity in English (in some cases, the official language of the country to be exported). For detailed information, please contact Mitutoyo in advance.

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Please follow the official instruction in each community and country.

Disposal of Old Electrical & Electronic Equipment (Applicable in the European Countries with Separate Collection Systems)



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To reduce the environmental impact and minimize the volume of landfills, please cooperate in reuse and recycle.

For how to dispose of the product, please contact the agent where you purchased the product or a Mitutoyo sales office.

China RoHS Compliance Information

This product meets China RoHS requirements. See the table below.

产品中有害物质的名称及含量

| | | | 有害 | 物质 | | |
|--------|------|------|------|----------|-------|--------|
| 部件名称 | 铅 | 汞 | 镉 | 六价铬 | 多溴联苯 | 多溴二苯醚 |
| | (Pb) | (Hg) | (Cd) | (Cr(VI)) | (PBB) | (PBDE) |
| 本体 | 0 | 0 | 0 | 0 | 0 | 0 |
| 电气设备部分 | × | 0 | 0 | 0 | 0 | 0 |
| 配件 | 0 | 0 | 0 | 0 | 0 | 0 |

本表格依据 SJ/T 11364 的规定编制。

○:表示该有害物质在该部件所有均质材料中的含量均在 GB/T 26572 规定的限量要求以下。

×:表示该有害物质至少在该部件的某一均质材料中的含量超出 GB/T 26572 规定的限量要求。



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另外,此期限不同于质量/功能的保证期限。

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If this product fails or is damaged for any of the following reasons, it will be subject to a repair charge, even if it is still under warranty.

- Failure or damage owing to fair wear and tear
- Failure or damage owing to inappropriate handling, maintenance or repair, or to unauthorized modification
- Failure or damage owing to transport, dropping, or relocation of the product after purchase
- Failure or damage owing to fire, salt, gas, abnormal voltage, lightning surge, or natural disaster
- Failure or damage owing to use in combination with hardware or software other than those designated or permitted by Mitutoyo
- · Failure or damage owing to use in ultra-hazardous activities

This warranty is effective only where the product is properly installed and operated in conformance with the instructions in this document within the original country of the installation.

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About This Document

Positioning of this document, document map

This describes the positioning of this document and its relationship with other installments.

| Laser Scan Micrometer | |
|---------------------------|--|
| <controller></controller> | |
| User's Manual | |

Laser Scan Micrometer <Sensor> User's Manual

IF Module for LSM Controller <PROFINET> User's Manual (This document) Describes use of LSMPAK to set up and operate the controller of the Laser Scan Micrometer.

Describes the sensor of the Laser Scan Micrometer, including how to connect it to the controller and its specifications.

Describes the IF Module for LSM Controller <PROF-INET> which is attached to the controller of the Laser Scan Micrometer, including its attachment to the controller and specifications.

Intended readers and purpose of this document

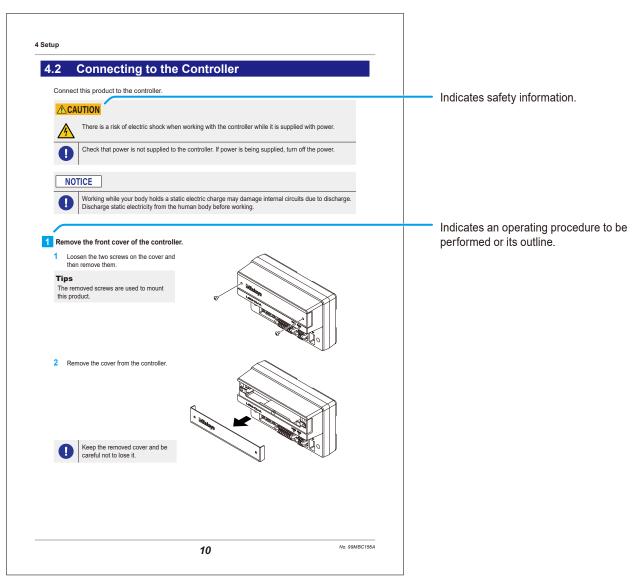
Intended readers

This document is intended for operators and administrators of the Laser Scan Micrometer. The readers are assumed to have been familiar with basic operations on a PC and Windows. They are also assumed to be able to understand individual instructions by reading the described drawings.

Purpose

The purpose of this document is to help you to understand the functional overview of the product, the functions of each part, the non-contact type sensor using a laser beam, operation procedures, and maintenance details.

How to read this document



Brackets, quotation marks and numbers (1, 1)

The meanings of brackets, quotation marks and numbers to be used in this document are as follows.

| (): Round brackets | Represent a paraphrase of an immediately preceding phrase or a supple- mentary explanation. | |
|---------------------------------|--|--|
| " ": Double quotation marks | Represent a highlighted phrase. They also indicate an index where infor- mation to be referenced is described. | |
| []: Square brackets | Represent a menu name on the screen, screen name, dialog name, button, display item, tab name, or key on the keyboard. They also indicate an item to be purposely entered or selected by the customer. | |
| <mark>1, 2, 3</mark> 1, 2, 3 | Indicates the order and the contents of tasks. (1: indicates main tasks, 1: indicates detailed tasks) | |

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1 Introduction

This product is an IF module that enables data communication using PROFINET.

1.1 About PROFINET

PROFINET is an Ethernet standard for industrial use. The specification is managed by PROFIBUS & PROFINET International and is freely available. In Japan, the Japanese Profibus Organization conducts promotional activities and certification testing.

PROFINET communicates using standard Ethernet technology. Therefore, it can coexist on a network along with Ethernet.

PROFINET provides two types of data communication: PROFINET CBA and PROFINET IO.

PROFINET CBA is component-based communication that is mainly used for communication between intelligent devices such as PROFINET controllers.

PROFINET IO is a communication method used for I/O control data, and is designed to support the following three communication methods of different performance levels.

- NRT (Non Real-time): Asynchronous communication based on TCP/IP.
- RT (Real-time): Cyclic communication with a period of about 4 msec.
- IRT (Isochronous Real-time): Cyclic communication with a shorter period than RT.

Data communication by PROFINET IO is based on the provider/consumer model. The side sending the data is called the "provider" and the side receiving the data is called the "consumer". PROFINET also includes I/O controllers (such as PLCs) and I/O devices among its system components. I/O controllers and I/O devices can be providers or consumers, depending on which device sends the data.

I/O devices are connected to one or more I/O controllers via PROFINET IO.

1.2 Features of This Product

This product connects to the LSM controller and is used together with the LSM controller and sensors connected to the controller to form an LSM system.

This product acts as an I/O device for PROFINET for communication with devices (such as PLCs) that function as PROFINET controllers.

PROFINET performance corresponds to the RT communications level, enabling control of LSM sensors and acquisition of measurement data from the PROFINET I/O controller using cyclic communication.

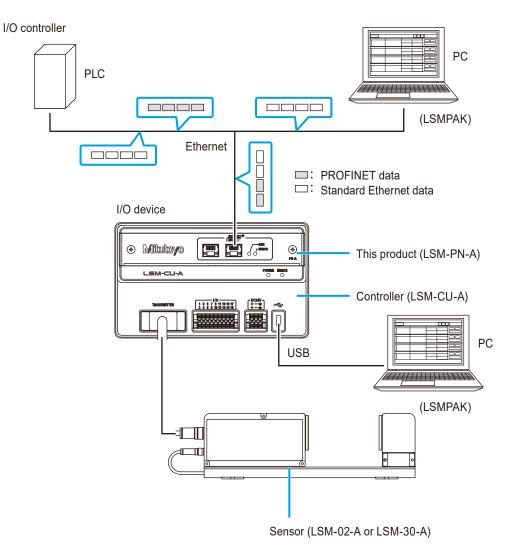
For details about cyclic communication, see 🗐 "5.1 Communication Specification" on page 15.

For details about the controller, see 🔲 "Laser Scan Micrometer <Controller> User's Manual" (separate document).

For details about the sensor, see 💷 "Laser Scan Micrometer <Sensor> User's Manual" (separate document).

1.3 LSM System Diagram

The following is an example of a system configuration with this product connected with the controller.



Devices required for system configuration

| Device name | Remarks |
|-----------------|--|
| This product | This product is an optional accessory for controller LSM-CU-A. It is |
| | used in combination with the controller. This product enables PROF- |
| | INET communication. |
| | For details, see 📃 "7.3 Measurement Configurations Usable with |
| | This Product" on page 41. |
| Controller | The controller LSM-CU-A controls the Laser Scan Micrometer. |
| | For details about the controller, see 🗐 "Laser Scan Micrometer |
| | <controller> User's Manual" (separate document).</controller> |
| Sensor | This is the sensor unit of the Laser Scan Micrometer. LSM-02-A |
| | (0.005 mm–2 mm) or LSM-30-A (0.3 mm–30 mm) can be used. |
| | For details, see 💷 "Laser Scan Micrometer <sensor> User's Manual"</sensor> |
| | (separate document). |
| LSMPAK (PC) | This is software used for controlling the controller. It is installed for |
| | use on a personal computer. |
| | The personal computer on which LSMPAK is installed is connected to |
| | the controller through a USB or Ethernet connection. |
| | For details about the controller, see 💷 "Laser Scan Micrometer |
| | <controller> User's Manual" (separate document).</controller> |
| I/O controller | The I/O controller is a device that communicates with this product, |
| (PLC, PC, etc.) | and is an I/O device in PROFINET communication. |
| | Typical I/O controllers include devices such as PLCs. |

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2 Unpacking and Checking

After unpacking this product, first check the following.

- No missing parts (including the product and all accessories)
- No damage was sustained during transit

We take all possible measures to ensure the quality of our products, but in the unlikely event that you discover a missing or damaged product, please contact your nearest Mitutoyo sales office.

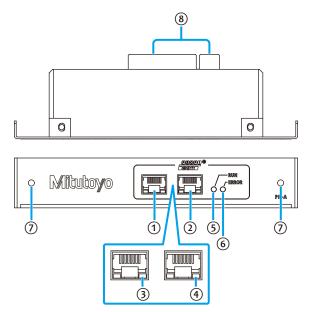
This product and included accessories

| | Part No. | Name | Quantity |
|----------|--|-------------------------------------|----------|
| 02 | 02AGQ360 IF Module for LSM Controller <profinet> (this product)</profinet> | | 1 |
| 99 | MBC157B | Quick Start Manual | 1 |
| 02NGA062 | | CD-ROM | 1 |
| 02NGA074 | | LSM-PN-A device file | — |
| | 99MBC156J/A | User's Manual (PDF) (this document) | |
| WA140 | | General product warranty (large) | 1 |

MEMO

3 Part Names and Functions

This chapter describes the name and function of each part of this product.



| No. | Name | Function | Reference |
|-----|----------------------------|--|-----------|
| 1 | RJ-45 connector (port 1) | These are Ethernet ports. | 5.2.1 |
| 2 | RJ-45 connector (port 2) | Connect to them with communication cables (Ethernet cables). | |
| 3 | Link/activity LED (port 1) | Indicates the status of communications. | |
| 4 | Link/activity LED (port 2) | | |
| 5 | RUN indicator | Indicates this product's operating status, network status, and status of communication | |
| 6 | ERROR indicator | with the I/O controller (PLC, etc.). | |
| 7 | Mounting hole | Used for mounting the controller. | 4.2 |
| 8 | Edge connector | Insert into the socket of the controller. | |

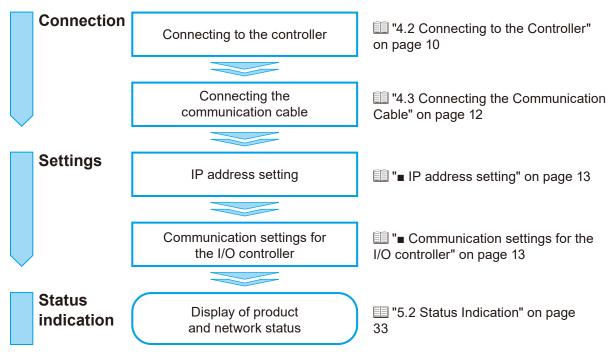
MEMO

4 Setup

Use the following procedure to connect this product and the system devices and configure the settings.

4.1 Work Flow

This section describes the work flow.



No. 99MBC156A

4.2 Connecting to the Controller

Connect this product to the controller.



There is a risk of electric shock when working with the controller while it is supplied with power.



Check that power is not supplied to the controller. If power is being supplied, turn off the power.

NOTICE



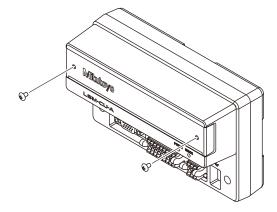
Working while your body holds a static electric charge may damage internal circuits due to discharge. Discharge static electricity from the human body before working.

Remove the front cover of the controller.

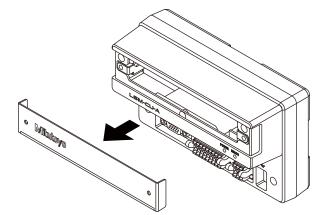
1 Loosen the two screws on the cover and then remove them.

Tips

The removed screws are used to mount this product.



2 Remove the cover from the controller.



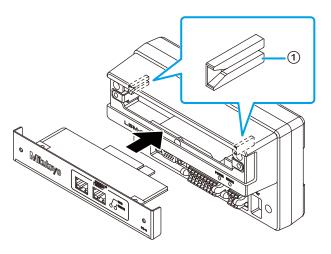


Keep the removed cover and be careful not to lose it.

4 Setup

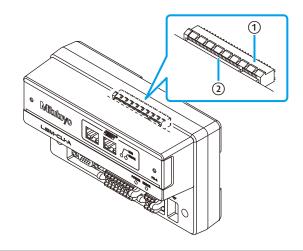
2 Mount this product on the controller.

1 Insert this product along the guides on either side of the controller.



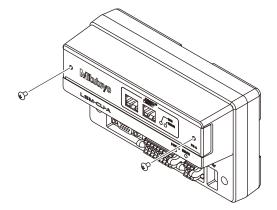
| No. | Name |
|-----|-------|
| 1 | Guide |

2 Insert the edge connector of this product into the socket of the controller.



| No. | Name |
|-----|----------------|
| 1 | Socket |
| 2 | Edge connector |

3 Fasten with the two screws removed in step 1.



4.3 Connecting the Communication Cable

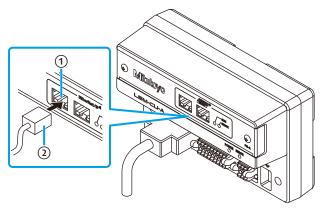
Connect the communication cable to this product.

4.3.1 How to Connect the Communication Cable

Tips

- Use an STP cable of Cat.5e or higher for the communication cable.
- This product is compatible with Auto MDI-X, which automatically detects whether the cable type is straight or cross for communication.
- This product does not support optical communication or single-pair Ethernet.
- Make sure that communication cable length does not exceed 30 m.

1 Connect the communication cable to one of the RJ-45 connectors (port 1 or port 2) on this product.



| No. | Name |
|-----|---------------------|
| 1 | RJ-45 connector |
| 2 | Communication cable |

2 Connect the other end of the communication cable to the RJ-45 connector on the network side.

4.4 **Device Settings**

This section describes the settings for network communication between this product and the I/O controller

IP address setting

IP address setting is required for network communication.

The IP address of this product is factory-set to 192.168.0.50.

The IP address can be changed in the following ways. Change the address according to the requirements of your network.

- Change using the configuration tool of I/O controller.
- Changing the IP address using the I/O controller's configuration tool, etc.

The device IP address can be changed using engineering tools such as that provided with the I/O controller. For instructions on how to use the tool, see the I/O controller manual.

Tips

- · When the I/O controller starts PROFINET communication, the IP address of this product is changed to the value specified by the I/O controller and the initial IP address is cleared.
- Ethernet connection can be made from LSMPAK to the IP address specified by the I/O controller.

Communication settings for the I/O controller

The settings required for PROFINET communication with this product are made by the engineering tool of the I/O controller. For information on how to operate the engineering tool, see the I/O controller manual.

The general setup process to be performed on the I/O controller is as follows.

Setting the device name

Each I/O device in PROFINET has a unique name and is identified within the system by that name. The device name of this product is set to "Ism-pn-a" at the factory. When using multiple units of this product on the same network, change the device name to avoid duplication.

Registering the device profile

Register the device profile of this product to the I/O controller.

Use the product's GSDML (XML-based General Station Description) file to register device profiles. Use the GSDML file stored on the included CD-ROM or download it from the Mitutoyo web site or the PI (PROFIBUS & PROFINET International) web site.

Setting the connection

Set the connection type (point-to-point/multicast), send and receive data size, transmission interval, etc.

Assigning device input/output data

Assign the data area to be sent/received by this product in the program variables using the engineering tool, etc.

MEMO

5 Communication Function

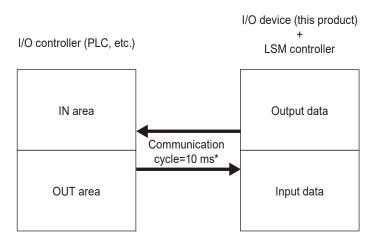
5.1 Communication Specification

5.1.1 **PROFINET** Communication

The I/O controller and this product communicate via PROFINET. This section provides an overview of PROFINET communication and details of the data used for communication.

Overview

The PROFINET I/O controller and this product perform cyclic data communication at a fixed cycle, and output and input data are exchanged according to the communication cycle. The communication cycle of this product can be set between 2 ms and 3200 ms.



* The communication cycle can be set on an individual basis.

After establishing PROFINET communication, the I/O controller periodically inputs and outputs data to and from I/O devices.

Details of data

Output data from this product to I/O controller

This product has two output data structures with different data identification numbers (ID Numbers): Basic (28 bytes) and Advanced (180 bytes).

With the Basic structure, data for a single measurement can be acquired from an I/O controller in one communication cycle, while the Advanced structure can return data for 20 measurements in a single communication cycle.

The ID Numbers defined in the GSDML file for this product are as follows: Basic=0x101 and Ad-vanced=0x102.

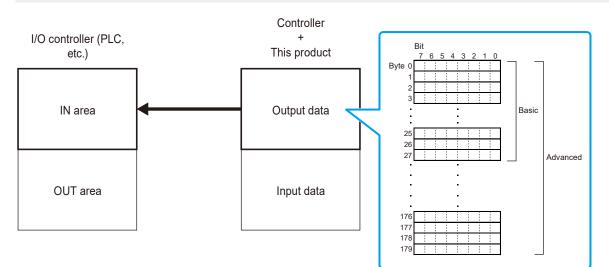
Tips

If the communication cycle between this product and the I/O controller is longer than the cycle for exchanging measurement data between the LSM controller and this product, measurement data may be lost on the I/O controller side.

The cycle of measurement data exchange between the LSM controller and this product depends on the number of averaging setting of the LSM controller.

Select Basic or Advanced and set the communication cycle between this product and the I/O controller according to the LSM controller's averaging frequency setting and the I/O controller's capability.

You can switch between Basic and Advanced and set the communication cycle between this product and the I/O controller using the I/O controller's configuration software. For details, see the I/O controller manual.



| Field type | TYPE | Byte | Bit | Description | Name | Current position display execution | Measurement execution |
|----------------|------|------|-----|---|-----------------------------|------------------------------------|--------------------------------|
| | | | 7 | N/A | N/A | | |
| | | | 6 | N/A | N/A | | |
| | | | 5 | Automatic workpiece detection | AUTO_DET | | |
| | | 0 | 4 | N/A | N/A | | |
| | | | 3 | N/A | N/A | | √ Error status record |
| | | | 2 | N/A | N/A | | |
| | | | 1 | Two items measurement | SUB | | |
| | | | 0 | Measuring | MEAS | | |
| Status bit 1*1 | BYTE | | 7 | N/A | N/A | Error record: | |
| | | | 6 | N/A | N/A | 4 bytes | 4 bytes |
| | | | 5 | N/A | N/A | | |
| | | | 4 | N/A | N/A | - | |
| | | 1 | 3 | N/A | N/A | - | |
| | | | 2 | Calibrating | CAL_OK | - | |
| | | | 1 | Offset state | OFST_NOW | - | |
| | | | 0 | Preset state | PRST NOW | - | |
| | | 2 | 7:0 | N/A | N/A | | |
| | | 3 | 7:0 | N/A | N/A | - | |
| | | | 7 | N/A | N/A | | |
| | | | 6 | Calibration error | CAL_ER | | ✓ Status record: 4 bytes |
| | | 4 | 5 | Statistics buffer overflow | STAT_OVF | | |
| | | | 4 | Overflow data | <u> </u> | | |
| | | | | | OVR_DATA | | |
| | | | 3 | Waste removal (overflow) | RMV_DUST_OVR | | |
| | | 5 | 2 | Waste removal | RMV_DUST | | |
| | | | 1 | Outlier elimination (all) | ABNML_DATA_OUT_ALL | | |
| | | | 0 | Outlier elimination | ABNML_DATA_OUT | | |
| | | | 7 | N/A | N/A | | |
| | | | 6 | N/A | N/A | | |
| | | | 5 | Edge error | EDGER | | |
| | | | 4 | Edge not detected | NOEDG | | |
| | | | 3 | No measurement sampling Measurement interruption | NO_SCAN_SIG EXT_MEAS_STP | | |
| | | | | from outside | | | |
| | | | 1 | Ring buffer overflow | RING_OVF | | |
| Status bit 2*1 | BYTE | | 0 | No workpiece | NO_WORK_PCS | √ Status record: | |
| Status pit Z | | | 7 | Dirt detection | DIRT_ER | 4 bytes | |
| | | | 6 | N/A | N/A | | |
| | | 6 | 5 | Watchdog error | WDTO_ER | 4 | |
| | | | 4 | LD overcurrent Amount of light memorize | LD_OC_ER LIT_INT_ER | _ | |
| | | | | error | | - | |
| | | | 2 | FPGA config. error | FPGA_ER | - | |
| | | | 1 | Measurement unit EEPROM load error | MEPRM_ER | | |
| | | | 0 | EEPROM load error | EPRM_ER | 4 | |
| | | | 7 | Total error | TOTAL_ER |] | |
| | | | 6 | Invalid setting | STCFT | | |
| | | | 5 | N/A | N/A | | |
| | | 7 | 4 | N/A | N/A | | |
| | | ' | 3 | N/A | N/A | | |
| | | | 2 | N/A | N/A | | |
| | | | 1 | N/A | N/A | | |
| | | | 0 | Power supply error | PWR_ER | 4 | |

5 Communication Function

| Field type | TYPE | Byte | Bit | Description | Name | Current position display execution | Measurement execution |
|--------------------------------|------|----------|------------|-------------------------------------|----------------------------|---------------------------------------|--------------------------|
| Not used | N/A | 8 | 7:0 | N/A | N/A | N/A | N/A |
| Notused | IN/A | 9 | 7:0 | N/A | N/A | N/A | N/A |
| | | | 7 | LSM processing in progress | BUSY | - | \checkmark |
| | | | 6 | N/A | N/A | N/A | N/A |
| | | | 5 | N/A | N/A | N/A | N/A |
| | | | 4 | N/A | N/A | N/A | N/A |
| | | 10 | 3 | Next data available | NEXT | - | \checkmark |
| | | | 2 | N/A | N/A | N/A | N/A |
| | | | 1 | Valid measurement data available | MDVLD | - | \checkmark |
| I/O bit | BYTE | | 0 | Valid display data available | DDVLD | \checkmark | - |
| | | | 7 | N/A | N/A | N/A | N/A |
| | | | 6 | | LT7 | - | ~ |
| | | | 5 | | LT6 | - | √ |
| | | | 4 | | LT5 | - | \checkmark |
| | | 11 | 3 | GO/NG judgment | LT4 | - | ✓ |
| | | | 2 | | LT3 | - | · √ |
| | | | 1 | - | LT2 | - | √ |
| | | | 0 | | LT1 | - | · |
| | | | - | Dehast request | <u> </u> | - | v |
| | | | 7 | Reboot request | RBTRQ | N1/A | N1/A |
| | | | 6 | N/A | N/A | N/A | N/A |
| | | | 5 | N/A | N/A | N/A | N/A |
| | | 12 | 4 | N/A | N/A | N/A | N/A |
| | BYTE | | 3 | Stream measurement | STRM | | |
| | | | 2 | Single measurement | SNGL | | |
| | | | 1 | Measurement start | RUN | | |
| | | | 0 | Current value display | DPVAL | | |
| I/O bit (echo back) | | | 7 | Endian switching | ENDN | | |
| | | | 6 | N/A | N/A | N/A | N/A |
| | | | 5 | N/A | N/A | N/A | N/A |
| | | 13 | 4 | Parameter setting change request | CHGPRM | | |
| | | | 3 | Error clear request | CLRRQ | | |
| | | | 2 | Preset request | PSTRQ | | |
| | | | 1 | Data reception OK | RCVOK | | |
| | | | 0 | Measured data request | DREQ | | |
| | | 14 | 7:0 | Parameter set number | PRM[7:0] | | |
| | | | 7 | N/A | N/A | N/A | N/A |
| | | | 6 | N/A | N/A | N/A | N/A |
| | BYTE | | 5 | N/A | N/A | N/A | N/A |
| Device control bit | | | 4 | N/A | N/A | N/A | N/A |
| (echo back) | | | 3 | N/A | N/A | N/A | N/A |
| | | | 2 | N/A | N/A | N/A | N/A |
| | | | 1 | N/A | N/A | N/A | N/A |
| | | | 0 | GO/NG judgment ON | TOLON | IN/A | 11/74 |
| | | | | | | | |
| Number of valid data bits*² | INT | 16 17 | 7:0 7:0 | Valid data quantity | NODT[15:0] (Big endian) | \checkmark | \checkmark |
| | | | | | | | |
| Sequential num- | UINT | 18 19 | 7:0 | Sequential number | SEQNO[15:0] (Big endian) | | |
| ber bits*2 | | | 7:0 | | | | |
| | | 20 | 7:0 | | | \checkmark | \checkmark |
| Data hita (data @*? | | 21 | 7:0 | Data | DATA01[31:0] (Big endian) | | Measured value |
| Data bits (data ①)*2 | | 22 | 7:0 | Dala | | Internal value ①: 4 bytes | 1: |
| | | 23 | 7:0 | | | 4 Dytes | 4 bytes |

| Field type | TYPE | Byte | Bit | Description | Name | Current position display execution | Measurement execution |
|------------------------|-------|---|-----|------------------------------|------------------------------|------------------------------------|---------------------------------------|
| | | 24 | 7:0 | GO/NG judgment information [| TOL01[15:0] (Big endian) | | √ |
| Data bits (data ①)*² | INT | 25 | 7:0 | | | - | GO/NG judgment result①: 2 bytes |
| | | 26 | 7:0 | | STS01[15:0] | - | |
| Data bits (data ①)*2 | INT | 27 | 7:0 | Status information | (Big endian) | | Data status①: 2 bytes |
| : | | : | : | : | ^ | | : |
| : | | : | : | : | | : | : |
| | FLOAT | 172 | 7:0 | | DATA20[31:0] (Big endian) | <u>_</u> | ✓ |
| Data bits (data 20) *2 | | 173 | 7:0 | | | | v Measured value @: |
| | | 174 | 7:0 | | | Internal value 20: | 4 bytes |
| | | 175 | 7:0 | | | 4 bytes | 4 bytes |
| | | 176 7:0 177 7:0 | | | | \checkmark | |
| Data bits (data @) *2 | INT | | 7:0 | GO/NG judgment information | TOL20[15:0] (Big endian) | - | GO/NG judgment result@: 2 bytes |
| | INT | 178 | 7:0 | | STS20[15:0] | | √ |
| Data bits (data 20) *2 | | | 179 | 7:0 | Status information | (Big endian) | - |

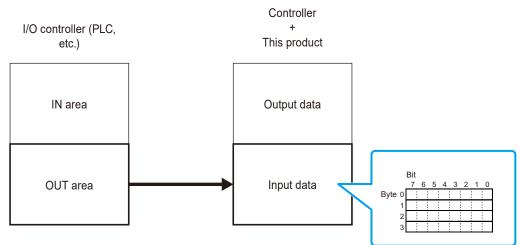
*1 To update the status, perform a measurement (RUN) or display current value (DPVAL) before referring to the status. Status information is not updated unless measurement (RUN) or current value display (DPVAL) is performed.

*2 Endian specification is available.

• Input data from I/O controller to this product

4-byte data (bytes 0 to 3) is received.

The Ident Numbers (data identification numbers) defined in the GSDML file for this product are Basic=0x201 and Advanced=0x202.



| Field type | TYPE | Byte | Bit | Description | Name | Current position display execution | Measurement execution |
|--------------------|------|------|-----|----------------------------------|----------|------------------------------------|--------------------------|
| | | | 7 | Reboot request | RBTRQ | √ | \checkmark |
| | | | 6 | N/A | N/A | N/A | N/A |
| | | | 5 | N/A | N/A | N/A | N/A |
| | | 0 | 4 | N/A | N/A | N/A | N/A |
| I/O bit | BYTE | 0 | 3 | Stream measurement | STRM | | |
| | | | 2 | Single measurement | SNGL | - | \checkmark |
| | | | 1 | Measurement start | RUN | - | \checkmark |
| | | | 0 | Current value display | DPVAL | \checkmark | - |
| | | 1 | 7 | Endian switching | ENDN | N/A | N/A |
| | | | 6 | N/A | N/A | N/A | N/A |
| | | | 5 | N/A | N/A | N/A | N/A |
| I/O bit | BYTE | | 4 | Parameter setting change request | CHGPRM | | |
| | | | 3 | Error clear request | CLRRQ | √ | \checkmark |
| | | | 2 | Preset request | PSTRQ | \checkmark | \checkmark |
| | | | 1 | Data reception OK | RCVOK | \checkmark | \checkmark |
| | | | 0 | Measured data request | DREQ | ✓ | \checkmark |
| Device control bit | BYTE | 2 | 7:0 | Parameter number | PRM[7:0] | | |
| Device control hit | | 3 | 7:1 | N/A | N/A | N/A | N/A |
| Device control bit | BYTE | | 0 | GO/NG judgment ON | TOLON | \checkmark | \checkmark |

• Functions of definition bits

This product \rightarrow I/O controller

| Field name | Size | Description | | | | |
|------------|---------|---|--|--|--|--|
| AUTO_DET | 1 bit | Auto Work Detect | | | | |
| | | Automatic workpiece detection | | | | |
| | | 1: ON | | | | |
| | | 0: OFF | | | | |
| BUSY | 1 bit | Busy | | | | |
| | | Access under way between IF module and LSM controller | | | | |
| | | 1: Access in progress | | | | |
| | | 0: No access | | | | |
| CAL_ER | 1 bit | Calibration Error | | | | |
| | | Calibration error | | | | |
| | | 1: Error occurred | | | | |
| | | 0: Normal | | | | |
| CAL_OK | 1 bit | Calibration Status | | | | |
| | | Calibration status display | | | | |
| | | 1: Calibration OK | | | | |
| | | 0: Not calibrated | | | | |
| DAT01 | 4 bytes | Data storage area | | | | |
| DAT02 | 4 bytes | | | | | |
| DAT03 | 4 bytes | | | | | |
| DAT04 | 4 bytes | | | | | |
| DAT05 | 4 bytes | | | | | |
| DAT06 | 4 bytes | | | | | |
| DAT07 | 4 bytes | | | | | |
| DAT08 | 4 bytes | | | | | |
| DAT09 | 4 bytes | | | | | |
| DAT10 | 4 bytes | | | | | |
| DAT11 | 4 bytes | | | | | |
| DAT12 | 4 bytes | | | | | |
| DAT13 | 4 bytes | | | | | |
| DAT14 | 4 bytes | | | | | |
| DAT15 | 4 bytes | | | | | |
| DAT16 | 4 bytes | | | | | |
| DAT17 | 4 bytes | | | | | |
| DAT18 | 4 bytes | | | | | |
| DAT19 | 4 bytes | | | | | |
| DAT20 | 4 bytes | | | | | |
| DDVLD | 1 bit | Valid Display Value | | | | |
| | | Display data availability indication | | | | |
| | | 1: Display data available | | | | |
| | | 0: Display data not available | | | | |
| DIRT_ER | 1 bit | Dirt Error | | | | |
| | | Sensor unit protective glass stain error | | | | |

| Field name | Size | Description | | | | | |
|------------|---------|--|--|--|--|--|--|
| EDGER | 1 bit | Edge Error | | | | | |
| | | Edge error (Occurs when, for example, an odd number of boundaries is | | | | | |
| | | detected on the measurement target.) | | | | | |
| | | 1: Error occurred | | | | | |
| | | 0: Normal | | | | | |
| EPRM_ER | 1 bit | EEPROM Error | | | | | |
| | | EEPROM load error | | | | | |
| | | 1: Error occurred | | | | | |
| | | 0: Normal | | | | | |
| FPGA_ER | 1 bit | FPGA Error | | | | | |
| | | FPGA configuration error | | | | | |
| | | 1: Error occurred | | | | | |
| | | 0: Normal | | | | | |
| LD_OC_ER | 1 bit | Laser Diode Over Current Error | | | | | |
| | | Measurement unit laser diode overcurrent error | | | | | |
| | | 1: Overcurrent detected | | | | | |
| | | 0: Normal | | | | | |
| LIT_INT_ER | 1 bit | Light Intensity Error | | | | | |
| | | Measurement unit laser diode brightness reduction error | | | | | |
| LT1 | 1 bit | Limit1 to Limit7 | | | | | |
| LT2 | 1 bit | GO/NG judgment LT1 to LT7 | | | | | |
| LT3 | 1 bit | * Corresponds to R1 to R7 of the Multi-Limit Selection function. | | | | | |
| LT4 | 1 bit | | | | | | |
| LT5 | 1 bit | | | | | | |
| LT6 | 1 bit | - | | | | | |
| LT7 | 1 bit | | | | | | |
| MDVLD | 1 bit | Valid Measurement Data | | | | | |
| | | Measurement data availability indication | | | | | |
| | | 1: Measurement data available | | | | | |
| | | 0: Measurement data not available | | | | | |
| MEAS | 1 bit | Measuring | | | | | |
| | | Measuring | | | | | |
| | | 1: Measuring | | | | | |
| | | 0: Idle | | | | | |
| EPRM_ER | 1 bit | Sensor EEPROM Error | | | | | |
| | | Measurement unit EEPROM load error | | | | | |
| | | 1: Error occurred | | | | | |
| | | 0: Normal | | | | | |
| NEXT | 1 bit | Next Data | | | | | |
| | | Next data availability indication | | | | | |
| | | 1: Next data available | | | | | |
| | ļ | 0: Next data not available | | | | | |
| NODT | 2 bytes | | | | | | |
| | | Measurement data quantity indication | | | | | |

| Field name | Size | Description |
|------------|---------|---|
| NOEDG | 1 bit | No Edge |
| | | Edge not detected error (Unable to properly detect boundary on the mea- |
| | | surement target.) |
| | | 1: Error occurred |
| | | 0: Normal |
| OFST_NOW | 1 bit | Offset |
| | | Offset state indication |
| | | 1: Offset set |
| | | 0: No offset |
| PRM[0:7] | 8 bit | Parameter Number Echo |
| | | Measurement parameter set number display (0x0 to 0xff) |
| | | * Up to 20 parameter sets can be stored. |
| PST_NOW | 1 bit | Preset |
| | | Preset state indication |
| | | 1: Preset set |
| | | 0: No preset |
| SEQNO | 2 bytes | Sequence Number |
| | | Sequence number assigned to the measurement data. |
| | | * This is a sequential number from 0 through 65535 that is incremented |
| | | each time the IF module acquires data from the LSM controller. Number- |
| | | ing returns to 0 upon reaching 65535. |
| STCFT | 1 bit | State Conflict Error |
| | | Setting mismatch |
| | | 1: Mismatch error |
| | | 0: Normal |
| | | * Raised upon incorrect bit operation. |
| STS01 | 2 bytes | STATUS ① to 29 |
| STS02 | 2 bytes | |
| STS03 | 2 bytes | 0x0002: Outlier elimination |
| STS04 | 2 bytes | 0x0004: Dirt removal process applied |
| STS05 | 2 bytes | 0x0008: Dirt removal process applied |
| STS06 | 2 bytes | 0x0010: Overflow data |
| STS07 | 2 bytes | 0x0020: Statistics buffer overflow |
| STS08 | 2 bytes | 0x0040: Calibration error |
| STS09 | 2 bytes | 0x0080: Outlier elimination CNT warning |
| STS10 | 2 bytes | 0x0100: ERR-0 No workpiece |
| STS11 | 2 bytes | 0x0200: Measurement ring buffer overflow |
| STS12 | 2 bytes | 0x0800: ERR-8 No measurement sampling |
| STS13 | 2 bytes | 0x1000: Edge not detected error (upon scan interrupt) |
| STS14 | 2 bytes | ov root. Eage not detected entry (upon scan interrupt) |
| STS15 | 2 bytes | |
| STS16 | 2 bytes | |
| STS17 | 2 bytes | |
| STS18 | 2 bytes | |
| STS19 | 2 bytes | |
| STS20 | 2 bytes | |

| Field name | Size | Description | | | | | |
|------------|---------|--|--|--|--|--|--|
| TOL01 | 2 bytes | GO/NG judgment ① to ⑳ | | | | | |
| TOL02 | 2 bytes | 1: Lower threshold exceeded (-NG) | | | | | |
| TOL03 | 2 bytes | 2: Within limits (GO) | | | | | |
| TOL04 | 2 bytes | | | | | | |
| TOL05 | 2 bytes | | | | | | |
| TOL06 | 2 bytes | For details about the controller, see 🗐 "Laser Scan Micrometer <control-< td=""></control-<> | | | | | |
| TOL07 | 2 bytes | ler> User's Manual" (separate document). | | | | | |
| TOL08 | 2 bytes | | | | | | |
| TOL09 | 2 bytes | | | | | | |
| TOL10 | 2 bytes | | | | | | |
| TOL11 | 2 bytes | | | | | | |
| TOL12 | 2 bytes | | | | | | |
| TOL13 | 2 bytes | | | | | | |
| TOL14 | 2 bytes | | | | | | |
| TOL15 | 2 bytes | | | | | | |
| TOL16 | 2 bytes | | | | | | |
| TOL17 | 2 bytes | | | | | | |
| TOL18 | 2 bytes | | | | | | |
| TOL19 | 2 bytes | | | | | | |
| TOL20 | 2 bytes | | | | | | |
| TOTAL_ER | 1 bit | Total Error | | | | | |
| | | Error status indication (determined from R-IN) | | | | | |
| | | 1: Error occurred | | | | | |
| | | 0: No error | | | | | |
| | | * All error causes are ORed for display. | | | | | |
| WDTO_ER | 1 bit | Watch Dog Time Out Error | | | | | |
| | | Watchdog timeout error | | | | | |
| | | 1: WDT timeout occurred | | | | | |
| | | 0: Error did not occur | | | | | |

I/O controller \rightarrow this product

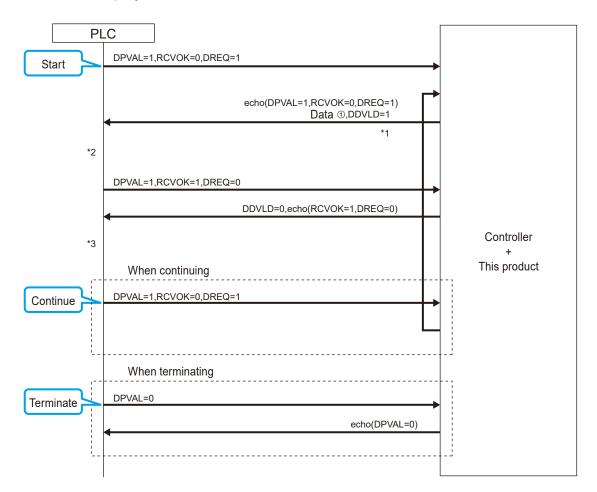
| Field name | Size | Description | | | | |
|------------|-------|--|--|--|--|--|
| CHGPRM | 1 bit | Change Parameter | | | | |
| | | Parameter setting change | | | | |
| | | 1: Change request | | | | |
| | | 0: No change request | | | | |
| | | * Changed on transition from $0 \rightarrow 1$. | | | | |
| CLRRQ | 1 bit | Clear Request | | | | |
| | | Error status clear request | | | | |
| | | 1: Clear request | | | | |
| | | 0: No clear request | | | | |
| | | * Cleared on transition from $0 \rightarrow 1$. | | | | |
| DPVAL | 1 bit | Display Value | | | | |
| | | Display value acquisition start | | | | |
| | | 1: Start display value acquisition | | | | |
| | | 0: Stop display value acquisition | | | | |

| Field name | Size | Description | | | | |
|------------|-------|--|--|--|--|--|
| DREQ | 1 bit | Data Request | | | | |
| | | Measured/displayed value data request | | | | |
| | | 1: Data request | | | | |
| | | 0: No data request | | | | |
| ENDN | 1 bit | Endian Swap | | | | |
| | | Endian selection | | | | |
| | | 1: Big endian | | | | |
| | | 0: Little endian | | | | |
| PRM[0:7] | 8 bit | Parameter Number | | | | |
| | | Specify parameter set numbers 0 to 19 (0x00 to 0xff) | | | | |
| PSTRQ | 1 bit | Preset Request | | | | |
| | | Preset request | | | | |
| | | 1: Preset request | | | | |
| | | 0: No preset request | | | | |
| | | * Set on transition from $0 \rightarrow 1$. | | | | |
| RBTRQ | 1 bit | Reboot Request | | | | |
| | | Device reset request | | | | |
| | | 1: Reset request | | | | |
| | | 0: No reset request | | | | |
| | | * Reset on transition from $0 \rightarrow 1$. | | | | |
| RCVOK | 1 bit | Receive OK | | | | |
| | | Measurement data reception complete | | | | |
| RUN | 1 bit | Run | | | | |
| | | Measurement start/stop | | | | |
| | | 1: Measurement start | | | | |
| | | 0: Measurement stop | | | | |
| SNGL | 1 bit | Single Measurement | | | | |
| | | Single measurement specification | | | | |
| | | 1: Single measurement | | | | |
| | | 0: Continuous-run measurement | | | | |
| STRM | 1 bit | Stream Measurement | | | | |
| | | Measurement data streaming acquisition | | | | |
| | | 1: Streaming acquisition | | | | |
| | | 0: Normal acquisition | | | | |
| TOLON | 1 bit | Tolerance On | | | | |
| | | GO/NG judgment ON/OFF | | | | |
| | | 1: GO/NG judgment ON | | | | |
| | | 0: GO/NG judgment OFF | | | | |

Communication method

This section describes how communication works from the I/O controller (PLC, etc.) to the I/O device (this product).

Idle value display



*1 Response (output data to IN area on the I/O controller (PLC, etc.))

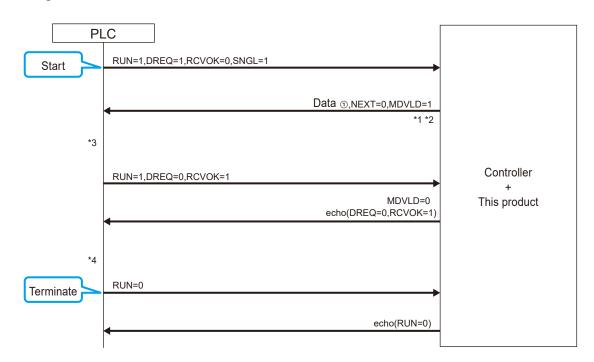
- Idle value 1: Bytes 20 to 23 data 1
- Status record: Bytes 4 to 7
- Error record: Bytes 0 to 3
- Valid data quantity: Bytes 16 to 17 (valid data quantity=1)
- *2 Processing on PLC side
 - Checks that DDVLD=1 was set.
 - Reads the valid data quantity to check the data count.
 - Reads in the number of pieces of data from data areas ① through 2 as written in the valid data quantity.
 - Sets the data reception OK flag.
 - RCVOK=1
 - DREQ=0

*3 Processing on PLC side

After confirming DDVLD=0, sets RCVOK=0.

5 Communication Function

Single measurement execution



*1 For single measurement: NEXT=0

*2 Response (output data to IN area on the I/O controller (PLC, etc.))

- Status record: Bytes 4 to 7
- Error record: Bytes 0 to 3
- Valid data quantity: Bytes 16 to 17
- Measured value ①: Bytes 20 to 23
- GO/NG judgment result of measured value (1): Bytes 24 to 25
- Data status of measured value (1): Bytes 26 to 27 $\,$

(When two items measurement is performed, the acquired two items of data are stored in the data ① and ① areas, respectively.)

For details about two items measurement, see 🗐 "Laser Scan Micrometer <Controller> User's Manual" (separate document).

*3 Processing on PLC side

- Checks that MDVLD=1 was set.
- Reads the valid data quantity to check the data count.
- Reads in the number of pieces of data from data areas ① through ⑳ as written in the valid data quantity. (When two items measurement is performed, the acquired two items of data are stored in the data ① to ⑩ and ⑪ to ⑳ areas, respectively.)

For details about two items measurement, see 🗐 "Laser Scan Micrometer <Controller> User's Manual" (separate document).

- Sets the data reception OK flag.
- RCVOK=1
- DREQ=0

*4 Processing on PLC side

After confirming MDVLD=0, sets RCVOK=0.

Continuous measurement execution

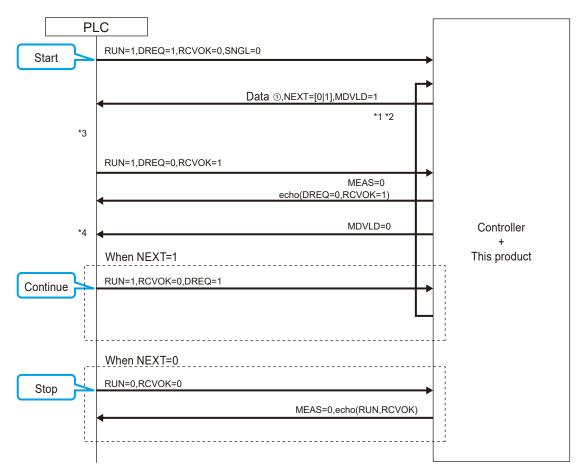
There are two methods for acquiring measurement data: normal acquisition, and streaming acquisition. Streaming acquisition allows measurement data acquisition at shorter intervals than normal acquisition. Use of streaming acquisition is recommended if the number of averaging is set to less than 4 times by the LSM controller.

For details about the number of averaging, see 📃 "Laser Scan Micrometer <Controller> User's Manual" (separate document).

IMPORTANT

Communication handshaking between the PLC and LSM is omitted during streaming acquisition, so data is not assured. If you want to detect missing data, create a PLC program to check using sequence numbers.

With normal acquisition



*1 NEXT=1 when the number of valid data is other than -1

*2 Response (output data to IN area on the I/O controller (PLC, etc.))

- Status record: Bytes 4 to 7
- Error record: Bytes 0 to 3
- Valid data quantity: Bytes 16 to 17
- Measured value ①: Bytes 20 to 23
- GO/NG judgment result of measured value ①: Bytes 24 to 25
- Data status of measured value ①: Bytes 26 to 27

(When two items measurement is performed, the acquired two items of data are stored in the data ① and ⑪ areas, respectively.)

For details about two items measurement, see 📃 "Laser Scan Micrometer <Controller> User's Manual" (separate document).

*3 Processing on PLC side

- Checks that MDVLD=1 was set.
- Reads the valid data quantity to check the data count.

• Reads in the number of pieces of data from data areas ① through ⑳ as written in the valid data quantity. (When two items measurement is performed, the acquired two items of data are stored in the data ① to ⑩ and ⑪ to ⑳ areas, respectively.)

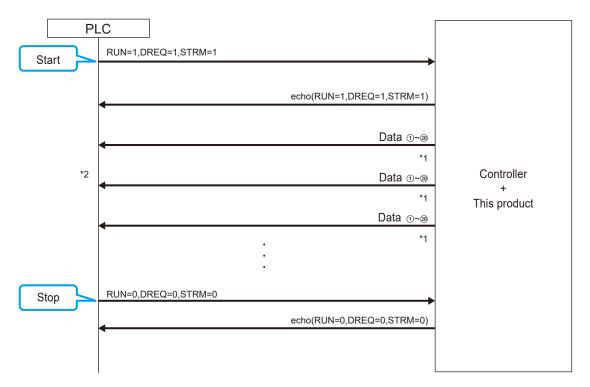
For details about two items measurement, see 📃 "Laser Scan Micrometer <Controller> User's Manual" (separate document).

• Sets the data reception OK flag. RCVOK=1 DREQ=0

*4 Processing on PLC side

After confirming MDVLD=0, sets RCVOK=0.

With streaming acquisition



*1 Response (output data to IN area on the I/O controller (PLC, etc.))

- Status record: Bytes 4 to 7
- Error record: Bytes 0 to 3
- Valid data quantity: Bytes 16 to 17
- Measured value ①: Bytes 20 to 23
- GO/NG judgment result of measured value ①: Bytes 24 to 25
- Data status of measured value ①: Bytes 26 to 27

(When two items measurement is performed, the acquired two items of data are stored in the data ① and ⑪ areas, respectively.)

For details about two items measurement, see 🛄 "Laser Scan Micrometer <Controller> User's Manual" (separate document).

*2 Processing on PLC side

Data is acquired by repeating the following steps.

Data is updated at the specified communication cycle, and SEQNO is incremented at each update.

- Check the sequence number (SEQNO) of the data.
- Reads the valid data quantity to check the data count.
- Reads in the number of pieces of data from data areas ① through ⑳ as written in the valid data quantity.
- (When two items measurement is performed, the acquired two items of data are stored in the data ① to ⑩ and ⑪ to ⑫ areas, respectively.)

For details about two items measurement, see 🗐 "Laser Scan Micrometer <Controller> User's Manual" (separate document).

• Reboot request

| PL | .C | |
|----------------|----------------|-------------------|
| Robert request | RBTRQ=1 | |
| Reboot request | echo(RBTRQ) *1 | |
| | | Controller + |
| *2 | | , This product |
| | RBTRQ=0 | |
| | echo(RBTRQ) *1 | |
| | | |

- *1 Depending on the timing, this response may not be received by PLC. This is because when RBTRQ is issued, the device enters reboot operation and echo(RBTRQ) becomes 0.
- *2 The RBTRQ bit should be held for at least one cycle of cyclic communication.

• Error clear request

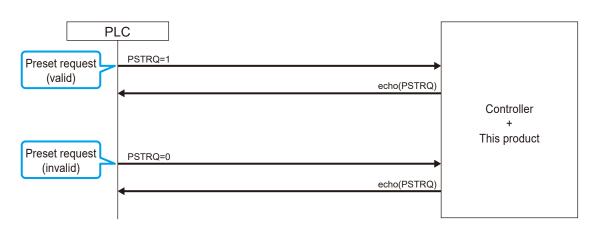
| | PLC | |
|------------------------|---------|-----------------|
| Error clear request | CLRRQ=1 | Controller + |
| | CLRRQ=0 | This product |

Tips

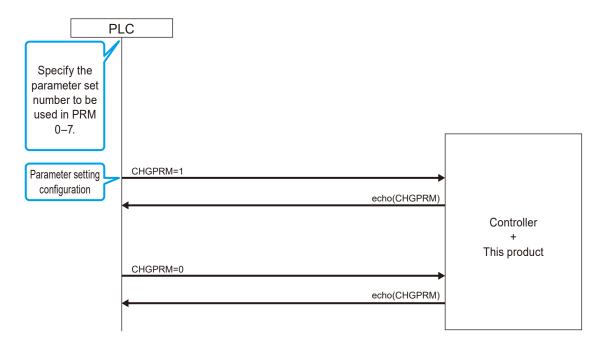
To update the error status after assertion of CLRRQ, set DPVAL ON and update the current value display.

5 Communication Function

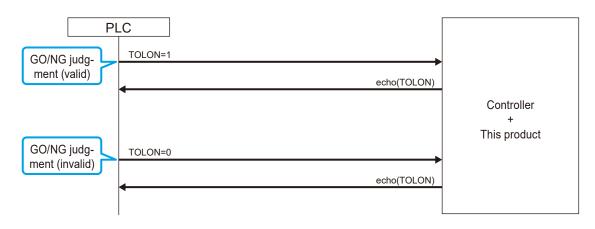
Preset request



• Parameter setting configuration

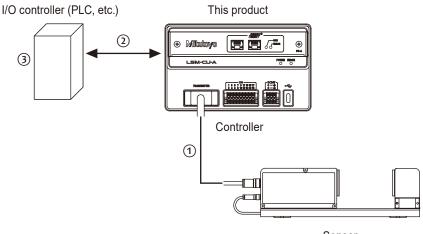


• GO/NG judgment setting



5.1.2 Duration of Data Processing

Time required from measurement execution to data processing by the I/O controller (PLC, etc.) is shown below.



Sensor

Maximum data processing time = (1 + (2) + (3))

- ① Response time of the controller
- ② RPI (transmission interval)
- ③ Scanning time of the I/O controller (PLC, etc.)
- ① For detail about response time of the controller, see 🗐 "Laser Scan Micrometer <Controller> User's Manual" (separate document).
- ② RPI is set by the configuration software on the I/O controller. The settable range is from 2 ms through 3200 ms.
- ③ Program scan time of the I/O controller varies according to processing capacity of the device and program size. Check specifications of the device used and program execution time.

Tips

If the I/O controller's scan time is shorter than the communication cycle, data may not be acquired correctly.

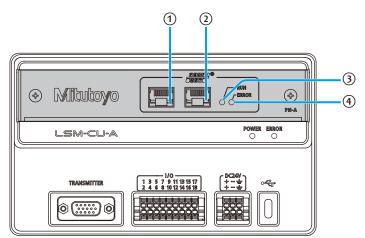
5.2 Status Indication

The status of the controller and network can be checked with the LEDs on this product or with LSMPAK.

For details about LSMPAK, see 🗐 "Laser Scan Micrometer <Controller> User's Manual" (separate document).

5.2.1 LED Indicators on This Product

The LED indications of this product change according to the status of the controller and network.



| No. | Name | Applica- tion | Indicator color | | Description |
|-----|-------------------|------------------|---|---|--|
| 1 | Link/activity LED | Ethernet | Off | | Communication is not available. |
| | (port 1) | | Steady yellow | - | Lights when a link is established and flashes during transmission and reception. |
| 2 | Link/activity LED | Ethernet | Off | | Communication is not available. |
| | (port 2) | | Steady yellow | - | Lights when a link is established and flashes during transmission and reception. |
| 3 | RUN | PROFINET | For indicator colors and their meanings, see 🗐 "■ Display | | |
| 4 | ERROR | PROFINET | color of PROFINET LEDs" on page 34. | | |

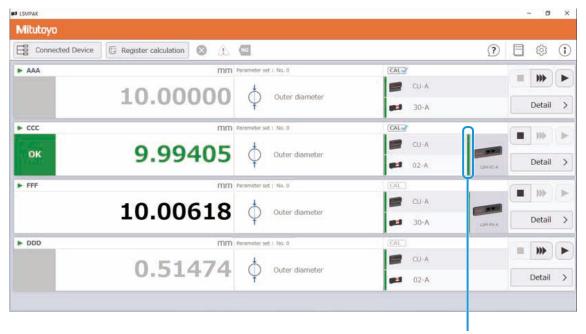
Display color of PROFINET LEDs

RUN and ERROR indicate the status by a combination of display colors. LED illumination states are shown in the table in order of highest priority toward the top.

| Indicator color | | | | Description | |
|---|-------|----------|--|---|--|
| RUN | l | ERROR | | Description | |
| Off | | Off | | Power is not being supplied to this product. | |
| Off | | Steady | | Unrecoverable error occurred in this product. Replacement | |
| | | red | | of this product may be required. | |
| Flashing | | Flashing | | System failure | |
| orange | | red | | Indicates an abnormality in the system. Status of communi- | |
| | | | | cation with the I/O controller (PLC, etc.) is unknown (normal | |
| | | | | or abnormal). | |
| | | | | Example: Controller and sensor are not connected. | |
| Flashing | | Flashing | | LED testing by DCP (Discovery and Configuration Protocol) | |
| green | | green | | is being performed using a tool. | |
| | | | | Example: When testing LEDs using a certification test tool, | |
| | | | | PROFINET Commander, or TIA Portal. | |
| Flashing | | Flashing | | Bus failure | |
| green | | red 🕂 | | Indicates an abnormality in the system. There is an abnor- | |
| | | | | mality in the status of communication with the I/O controller | |
| | | | - — – | (PLC, etc.). | |
| | · · · | | | Example: If different GSDML files are used in the program | |
| | | | | of I/O controllers (PLC, etc.). With the Ethernet cable un- | |
| | | | | plugged. Device name has not yet been set, etc. | |
| Steady | | Off | | I/O controller (PLC, etc.) is stopped for program mode. | |
| orange | | | | | |
| Steady | | Off | | Indicates an abnormality in the system. There is no abnor- | |
| le la | | | mality in the status of communication with the I/O controller (PLC, etc.). | | |

5.2.2 LSMPAK Screen

When this product is operating normally, the status LED lights green. (Red: Error occurred, Gray: Not working)



Status light

MEMO

6 Troubleshooting

If you cannot access the network, check the LED indicators.

For details about the LED indicators, see 📰 "5.2.1 LED Indicators on This Product" on page 33. For details about LSMPAK error messages, see 📰 "Laser Scan Micrometer <Controller> User's Manual" (separate document).

| Problem | Cause | Solution |
|--------------------------------------|--|--|
| Power does not go | This product is not properly inserted | Insert this product correctly into the |
| on. | into the socket of LSM-CU-A. | LSM-CU-A. |
| | | I "4.2 Connecting to the Controller" |
| | | on page 10 |
| Communication not | The cable is not properly connected. | Check cable connections and verify |
| working. | | that the link/activity LED is lit. |
| | The connected device is not turned | Make sure the connected device is |
| | on. | turned on and that the link/activity |
| | | LED is lit. |
| | Incorrect communication settings on | Check the LED indicators on the |
| | current device or connected device. | device and make communication |
| | | settings required to obtain a normal |
| | | lighting pattern. |
| | | For details on LED lighting patterns, |
| | | see 🗐 "5.2.1 LED Indicators on This |
| | | Product" on page 33. |
| | | For communication settings for the |
| | | connected device, see the manual or |
| | | other document related to that device. |
| Operation of this | This product is receiving electromag- | Eliminate the electromagnetic interfer- |
| product is unstable. | netic interference that exceeds the | ence. |
| Correct measure- | requirements of the EMC Directive | This product resumes normal opera- |
| ment values can- not be obtained. | and the UK Electromagnetic Compati- | tion after the electromagnetic interfer- |
| Communication | bility Regulations. | ence is eliminated. |
| errors occur. | | |
| This product re- | | |
| starts. | | |
| Operation of other | This product is being used in other | Implement countermeasures to pre- |
| devices is unstable. | than the intended operating environ- | vent electromagnetic interference with |
| This product is caus- | ment. | other devices. |
| ing loss of specified | This product generates electromag- | |
| functionality of other | netic emissions in an industrial envi- | |
| devices. | ronment. This product is not intended | |
| | for use outside of an industrial en- | |
| | vironment, and its use in residential | |
| | areas or other environments may | |
| | cause electromagnetic interference | |
| | with other devices. | |

MEMO

7 Specifications

This chapter describes the specifications of this product.

7.1 Basic Specifications

| Item | Specification | | | | |
|----------------------------|---|------------|-----------------------------|--|--|
| Code No. | 02AGQ350 | | | | |
| Model number | LSM-PN-A | | | | |
| Interface | LED | RUN | Dual Color LED1 (red/green) | | |
| | | ERROR | Dual Color LED2 (red/green) | | |
| | RJ45 connector | 2 channels | | | |
| Operating environ- ment | 0 °C to 50 °C, 20 % RH to 85 % RH (non-condensing) | | | | |
| Storage environ- ment | -10 °C to 60 °C, 20 % RH to 85 % RH (non-condensing) | | | | |
| CE marking/ | EMC Directive/Electromagnetic Compatibility Regulations: EN IEC 61326-1 | | | | |
| UKCA marking | Immunity test requirement: Clause 6.2 Table 2 | | | | |
| | Emission limit: Class A | | | | |
| | RoHS Directive/The Restriction of the Use of Certain Hazardous Substances in Electrical and Electronic Equipment Regulations : EN IEC 63000 | | | | |

7.2 Ethernet Communication Specifications

| ltem | Specification |
|--------------------|---|
| Communication port | RJ45×2 |
| Transmission speed | 100 Mbps, full duplex |
| Cable used | STP communication cables of type Cat.5e or higher |

7.2.1 PROFINET Function

| Function | Specification | |
|--------------------------------------|---|------------|
| PROFINET RT | PROFINET devices compliant with Conformance Class B | |
| | Media redundancy protocol (MRP) clients | |
| | Multicast providers and su | ubscribers |
| Minimum cycle time | 2 msec | |
| Maximum number of connections (AR*1) | 2 | |
| Number of CRs per I/O controller *2 | For periodic data | 2 |
| | For parameter setting | 1 |

*1 AR: Application Relation, AR type: Device Access

*2 CR: Communication Relation

7.3 Measurement Configurations Usable with This Product

Using this device, multiple LSM controllers can be connected to a network. Typical connection of multiple LSM controllers is shown below.

Networked LSM controllers can be managed from a PC using LSMPAK.

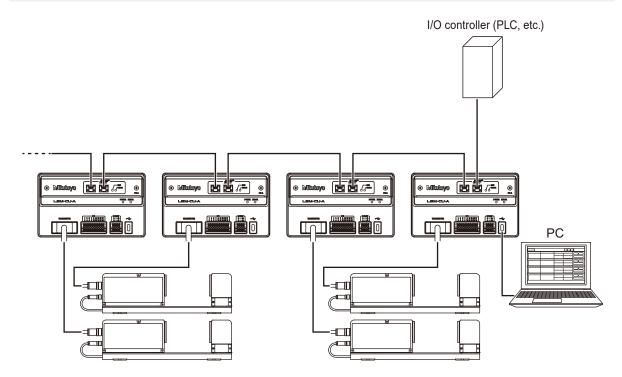
The maximum number of LSM controllers that can be managed using LSMPAK is eight.



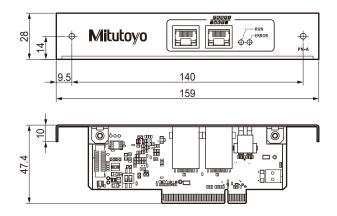
Duplicate IP addresses within the same network will result in incorrect communication. Please be careful to avoid setting duplicate IP addresses.

Tips

It does not matter whether you use port 1 or port 2 of this product to configure the network.



7.4 External Dimensions Drawing



Unit: mm

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Revision Record

| Date of publication | Revision status | Details of revision |
|---------------------|-----------------|---------------------|
| June 1, 2023 | First edition | Publication |

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